

Nonlinear Analysis of Direct Sampling Mixer using F-matrix

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Content

- Background
- Analysis with Fundamental Matrix
 - Nonlinear System
 - Periodic Time-Variant System
- Analysis of Charge Sampling Circuit
- Simulation
- Conclusion and Future Work

Content

■ Background

■ Analysis with Fundamental Matrix

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- Periodic Time-Variant System

■ Analysis of Charge Sampling Circuit

■ Simulation

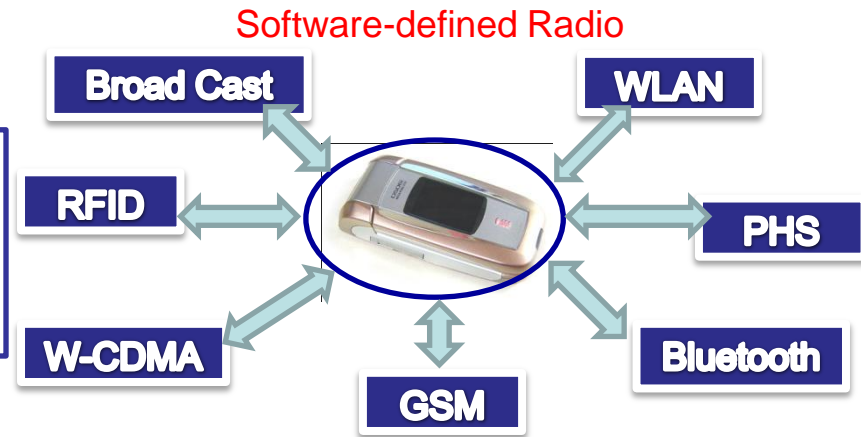
■ Conclusion and Future Work

Background

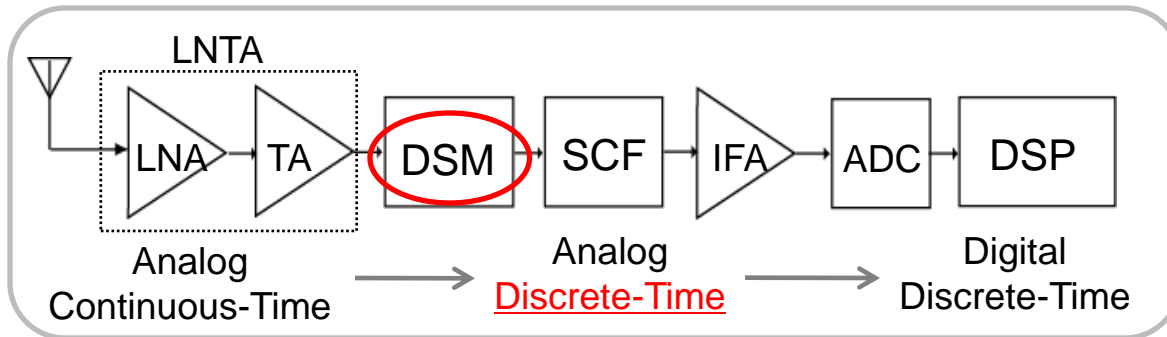
◆ Software-defined Radio

➤ System with various modulation method and frequency on a RF circuit.

⇒ **Software-defined Radio**



➤ Discrete Time Receiver



TA : Voltage \Rightarrow Current
DSM : charge sampling
decimation

SCF : RF Filtering

✓ Down conversion and decimation

⇒ Demand Moderation of ADC

✓ Discrete time processing

⇒ Reconfigurable Technology

• Power consumption
• Small size

Background

◆ Direct Sampling Mixers (DSM)

Features

■ Charge Sampling

⇒ Frequency Conversion

■ Charge Shared Filtering

⇒ RF Filtering

■ Decimation

⇒ Less power loss due to low speed ADC

■ MOS Switches and capacitors

⇒ One chipping operation

■ Reconfigurability

⇒ Filter response change easily.

Problem

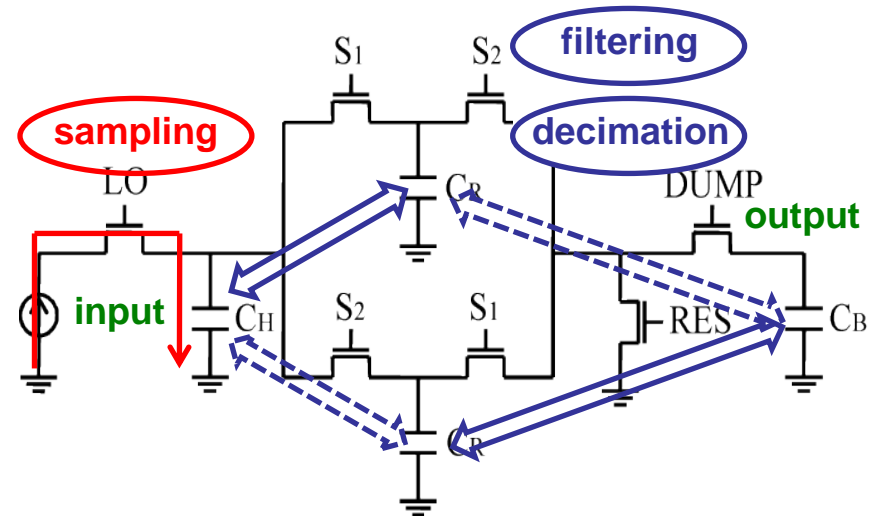
■ Noise-reduction

■ Improvement of filter property

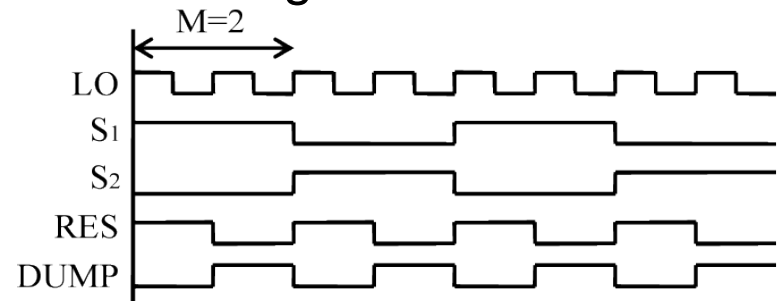
■ Nonlinear distortion

Research Propose : Design of distortion compensation method

• Basic of DSM



• Clock Timing Chart

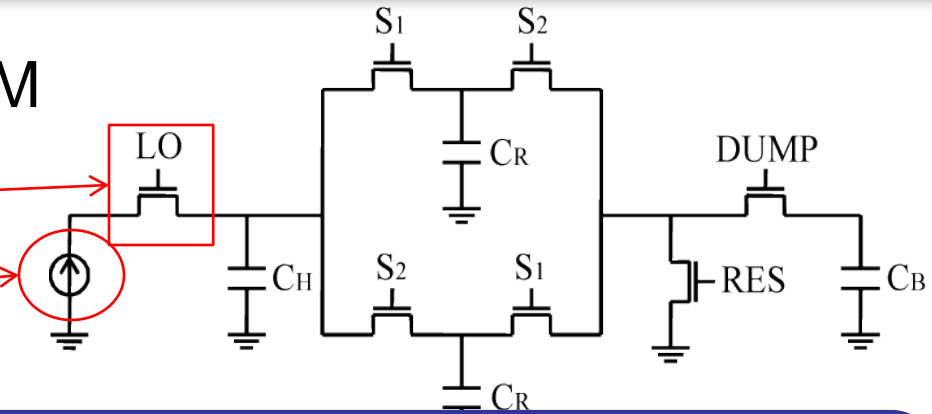


Background

◆ Complexity of Nonlinear DSM

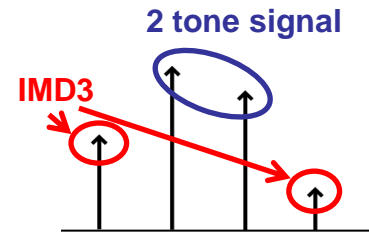
Nonlinear MOS Switch

Nonlinear TA



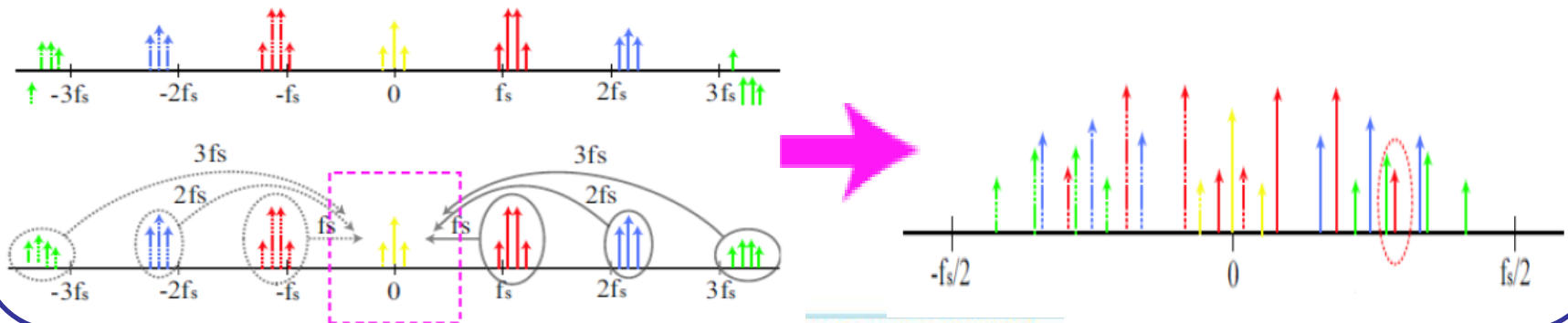
Memory Effect

DSM has **frequency characteristic (memory effect)**, so nonlinearity is expressed as a function of not only amplitude, also operation frequency.



Periodic Time-Variant System

Periodic time-variant system has **frequency conversion.**



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Analysis with Fundamental Matrix

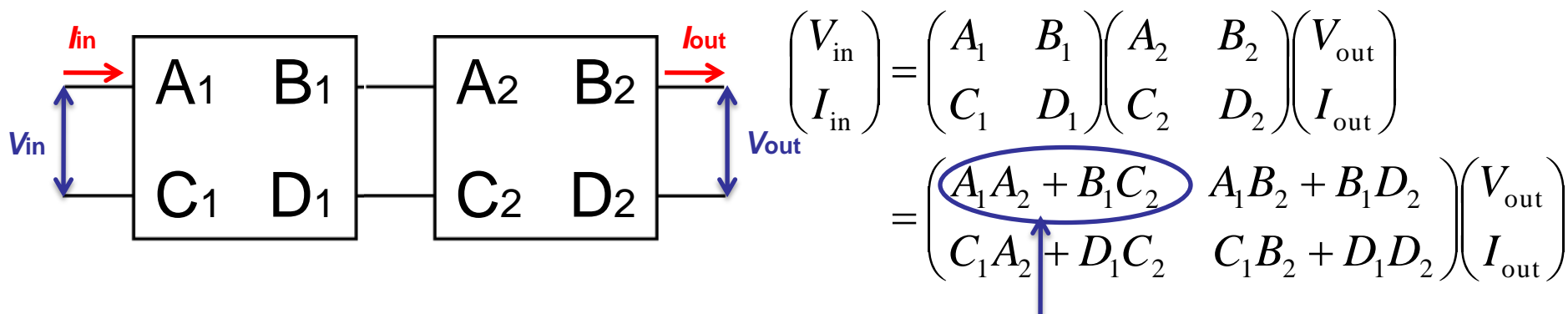
◆ New Analysis Method

The frequency conversion and Volterra series function are introduced into **Fundamental matrix**.

Advantage

- Complex circuit can be divided into some F-matrix. ⇒ flexibility
- Calculation of cascade connection is matrix calculation. ⇒ easy

• Cascade Connection with F-matrix



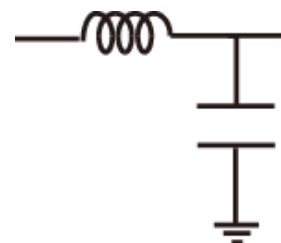
Inverse of (1, 1) component ⇒ Frequency Characteristic : V_{out}/V_{in}

Analysis with Fundamental Matrix

◆ Approach

Linear Time-Invariant :
LTI System (ex. LC Filter)

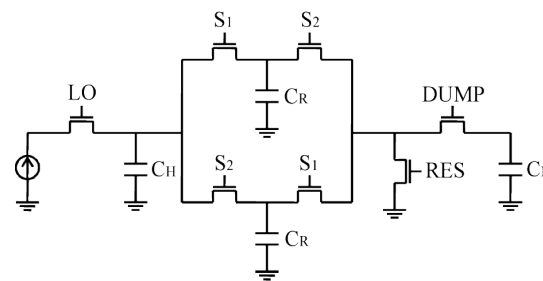
⇒ Conventional F-matrix target



Nonlinear Time-Invariant
System (ex. PA)

Linear Periodic Time-Variant :
LPTV System (ex. Linear Mixer)

Nonlinear Periodic Time-Variant :
NLPTV system (ex. Nonlinear Mixer, DSM)



Nonlinear System

◆ Volterra Series Function

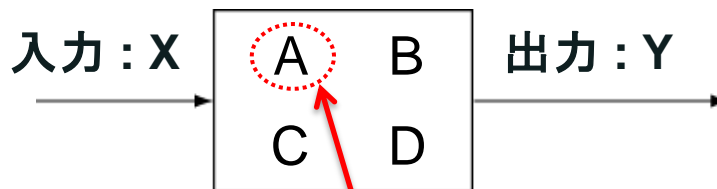
- Overall property of DSM can't be expressed as power series function because DSM have frequency characteristic . ⇒ **Volterra Series**

Volterra Series Function

$$\begin{aligned} Y(\omega) &= H_1(\omega) X(\omega) \\ &+ \int H_2(\omega_1, \omega - \omega_1) X(\omega_1) X(\omega - \omega_1) d\omega_1 \\ &+ \iint H_3(\omega_1, \omega_2, \omega - \omega_1 - \omega_2) X(\omega_1) X(\omega_2) X(\omega - \omega_1 - \omega_2) d\omega_1 d\omega_2 \end{aligned}$$

➔ **Multidimensional Transfer Function**

- Expression of F-matrix



$$\begin{pmatrix} V_X(\omega) \\ I_X(\omega) \end{pmatrix} = \begin{pmatrix} A & B \\ C & D \end{pmatrix} \cdot \begin{pmatrix} V_Y(\omega) \\ I_Y(\omega) \end{pmatrix}$$

$A_1(\omega_1), A_2(\omega_1, \omega_2), A_3(\omega_1, \omega_2, \omega_3)$

← This **A** has each dimensional functions

Nonlinear System

◆ Cascade Connection of Volterra Series



$$\begin{aligned} \mathbf{G} &: \mathbf{X} \Rightarrow \mathbf{Y} \\ \mathbf{H} &: \mathbf{Y} \Rightarrow \mathbf{Z} \\ \mathbf{F} &: \mathbf{X} \Rightarrow \mathbf{Z} \end{aligned}$$

$$\begin{pmatrix} V_X(\omega) \\ I_X(\omega) \end{pmatrix} = \begin{pmatrix} \mathbf{G} & 0 \\ 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} \mathbf{H} & 0 \\ 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} V_Z(\omega) \\ I_Z(\omega) \end{pmatrix} = \begin{pmatrix} \mathbf{G} \cdot \mathbf{H} & 0 \\ 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} V_Z(\omega) \\ I_Z(\omega) \end{pmatrix}$$

Eq. 1

$$F_1(\omega_1) = G_1(\omega_1)H_1(\omega_1)$$

$$F_2(\omega_1, \omega_2) = G_1(\omega_1 + \omega_2)H_2(\omega_1, \omega_2) + G_2(\omega_1, \omega_2)H_2(\omega_1)H_1(\omega_2)$$

$$F_3(\omega_1, \omega_2, \omega_3) = G_1(\omega_1 + \omega_2 + \omega_3)H_3(\omega_1, \omega_2, \omega_3)$$

$$+ \frac{2P\langle G_2(\omega_1, \omega_2 + \omega_3)H_2(\omega_2, \omega_3)H_1(\omega_1) \rangle}{3}$$

$$+ G_3(\omega_1, \omega_2, \omega_3)H_1(\omega_1)H_1(\omega_2)H_1(\omega_3)$$

[where $P\langle \ \rangle$: permutation operation ($\omega_1, \omega_2, \omega_3$)]

Periodic Time-Variant System

◆ Linear Periodic Time-Variant (LPTV) System

PTV transfer function : $H(\omega, t)$

$$y(t) = H(\omega, t)x(t)$$

$$H(\omega, t) = H(\omega, t + T)$$

$\left\{ \begin{array}{l} x(t) : \text{input} \\ y(t) : \text{output} \\ T : \text{time period} \end{array} \right.$



Fourier series expansion (Eq. 2)

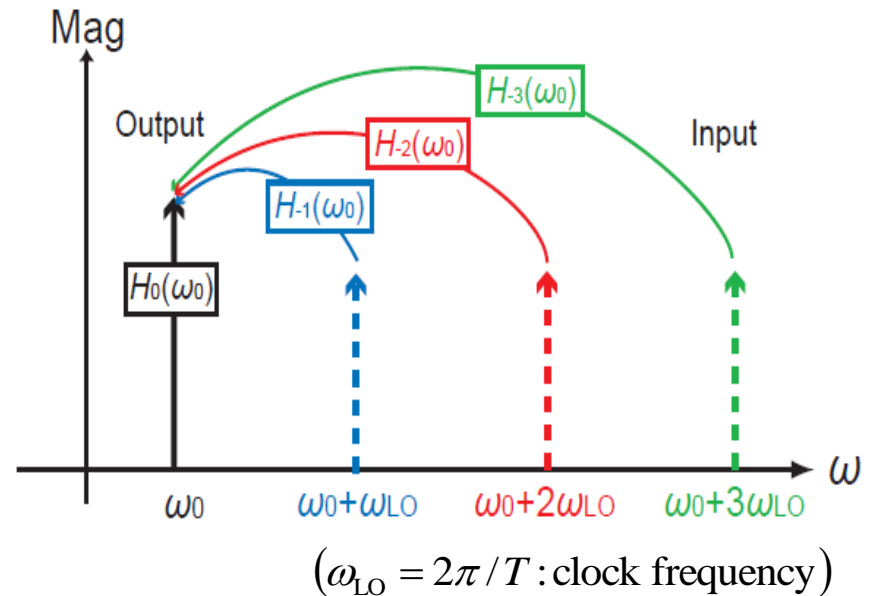
$$H(\omega, t) = \sum_n H_n(\omega) e^{jn\omega_{LO}t}$$

$$H_n(\omega) = \frac{1}{T} \int_0^T H(\omega, t) e^{-jn\omega_{LO}t} dt$$



$$y(t) = \sum_n H_n(\omega) e^{jn\omega_{LO}t} \cdot x(t)$$

➤ Frequency Conversion



Fourier Transform

$$Y(\omega) = \sum_n H_n(\omega) X(\omega - n\omega_{LO})$$

Frequency Conversion

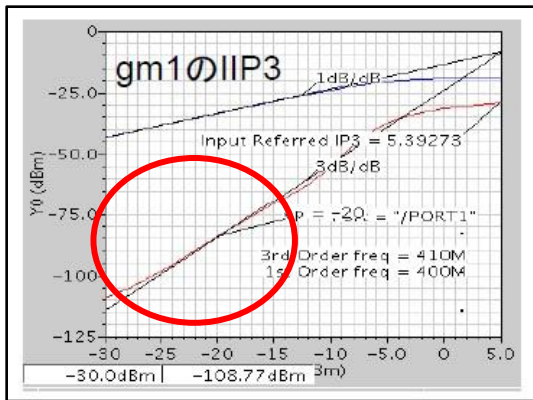
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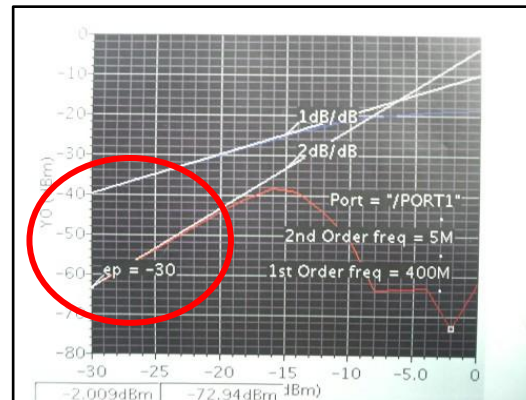
Analysis of Charge Sampling Circuit

◆ Nonlinearity of TA

➤ Power series expansion is approximated from measurement of the prototype TA.



✓IP3 → 3rd coefficient

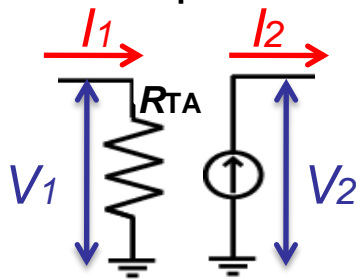


✓IP2 → 2nd coefficient

$$I_{TA}(t) = g_{m1}V_{in}(t) + g_{m2}\{V_{in}(t)\}^2 + g_{m3}\{V_{in}(t)\}^3$$

$$\begin{cases} g_{m1} = 11.3 \text{ mA/V} \\ g_{m2} = -10.3 \text{ mA/V}^2 \\ g_{m3} = -86.1 \text{ mA/V}^3 \end{cases}$$

➤ F-matrix expression of nonlinear TA



$$\begin{pmatrix} V_1(\omega) \\ I_1(\omega) \end{pmatrix} = \begin{pmatrix} 0 & \mathbf{A} \\ 0 & \mathbf{A}/R_{TA} \end{pmatrix} \cdot \begin{pmatrix} V_2(\omega) \\ I_2(\omega) \end{pmatrix}$$

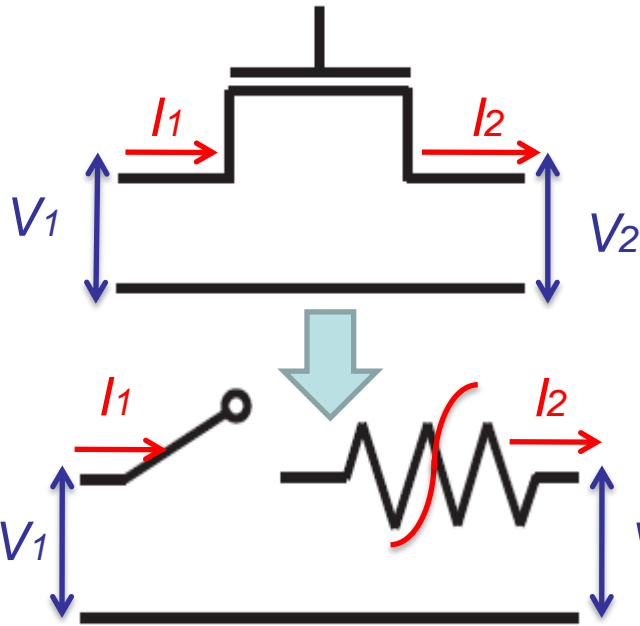
$$\begin{cases} a_1 = g_{m1}^{-1} \\ a_2 = -g_{m2}g_{m1}^{-3} \\ a_3 = -g_{m3}g_{m1}^{-4} + 2g_{m2}^2g_{m1}^{-5} \end{cases} \quad (\text{Eq. 3})$$

$$\mathbf{A} \cdot I_2(\omega) = a_1 I_2(\omega) + a_2 \int I_2(\omega_1) I_2(\omega - \omega_1) d\omega_1 + a_3 \int I_2(\omega_1) I_2(\omega_2) I_2(\omega - \omega_1 - \omega_2) d\omega_1 d\omega_2$$

Analysis of Charge Sampling Circuit

◆ Nonlinearity of MOS Switch

➤ MOS transistor is dealt as **ideal switch** and **nonlinear resistor**.



$$\text{ON state: } V_1(t) = V_2(t) + \frac{r_{\text{on1}} I_2(t) + r_{\text{on2}} \{I_2(t)\}^2 + r_{\text{on3}} \{I_2(t)\}^3}{1}$$



$$\text{OFF state: } V_1(t) = V_2(t) + \frac{r_{\text{off1}} I_2(t) + r_{\text{off2}} \{I_2(t)\}^2 + r_{\text{off3}} \{I_2(t)\}^3}{1}$$

➤ F-matrix expression of nonlinear MOS switch

$$\begin{pmatrix} V_1(\omega) \\ I_1(\omega) \end{pmatrix} = \begin{pmatrix} 1 & \mathbf{R}(t) \\ 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} V_2(\omega) \\ I_2(\omega) \end{pmatrix}$$

$$\left[\begin{aligned} \mathbf{R}(t) \cdot I_2(\omega) &= r_1(t) I_2(\omega) \\ &+ r_2(t) \int I_2(\omega_1) I_2(\omega - \omega_1) d\omega_1 \\ &+ r_3(t) \int I_2(\omega_1) I_2(\omega_2) I_2(\omega - \omega_1 - \omega_2) d\omega_1 d\omega_2 \end{aligned} \right]$$

➤ Nonlinear Resistor $\mathbf{R}(t)$ (Table.1)

r_{on1}	50 Ω	r_{off1}	1 M Ω
r_{on2}	-10 kV/A ²	r_{off2}	0
r_{on3}	-200 MV/A ³	r_{off3}	0

Analysis of Charge Sampling Circuit

◆ Analysis Procedure

1. Expression as F-matrix

$$\begin{pmatrix} V_{in}(\omega) \\ I_{in}(\omega) \end{pmatrix} = F_{TA} \cdot F_P \cdot F_{MOS} \cdot F_C \cdot \begin{pmatrix} V_{out}(\omega) \\ I_{out}(\omega) \end{pmatrix}$$



2. Matrix and Volterra series operation for cascade connection. (Eq.1)

$$F_{11} \Rightarrow G_1(\omega, t), G_2(\omega_1, \omega_2, t), G_3(\omega_1, \omega_2, \omega_3, t)$$



3. Derivation of Inverse of (1.1) component at F-matrix. (Appendix.1)

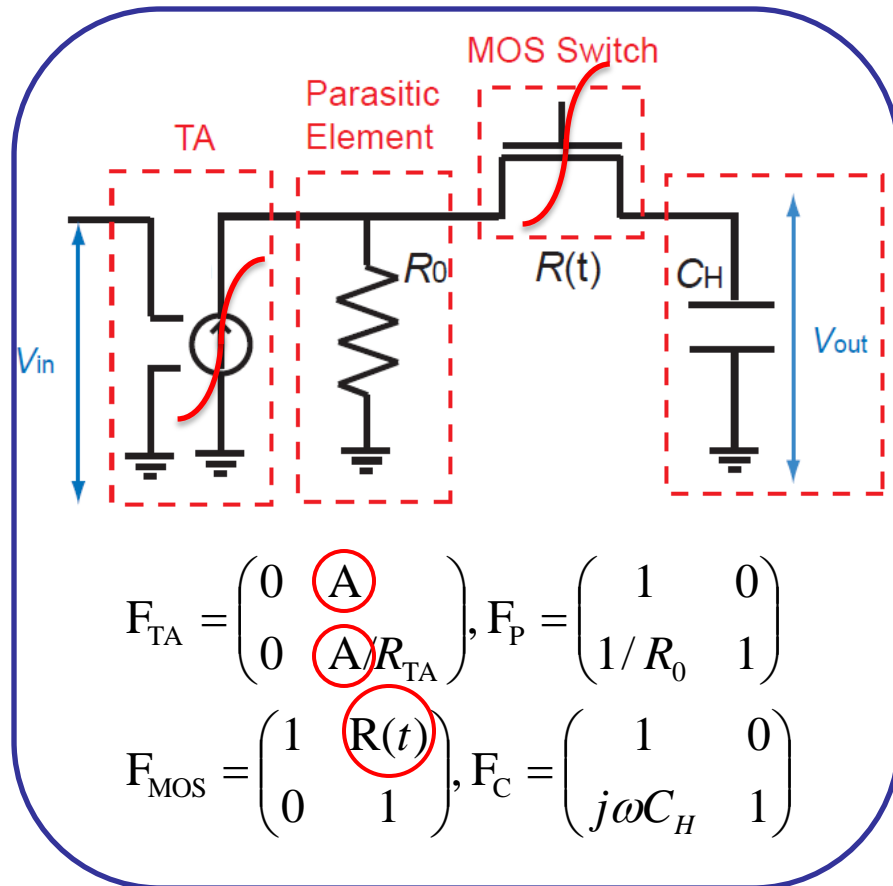
$$H_1(\omega, t), H_2(\omega_1, \omega_2, t), H_3(\omega_1, \omega_2, \omega_3, t)$$



4. Fourier series expansion. (Eq.2)

$$H_{n,1}(\omega), H_{n,2}(\omega_1, \omega_2), H_{n,3}(\omega_1, \omega_2, \omega_3)$$

➤ Charge Sampling Circuit



$$F_{TA} = \begin{pmatrix} 0 & \textcircled{A} \\ 0 & \textcircled{A/R_{TA}} \end{pmatrix}, F_P = \begin{pmatrix} 1 & 0 \\ 1/R_0 & 1 \end{pmatrix}$$

$$F_{MOS} = \begin{pmatrix} 1 & \textcircled{R(t)} \\ 0 & 1 \end{pmatrix}, F_C = \begin{pmatrix} 1 & 0 \\ j\omega C_H & 1 \end{pmatrix}$$

Multidimensional & PTV Transfer Function

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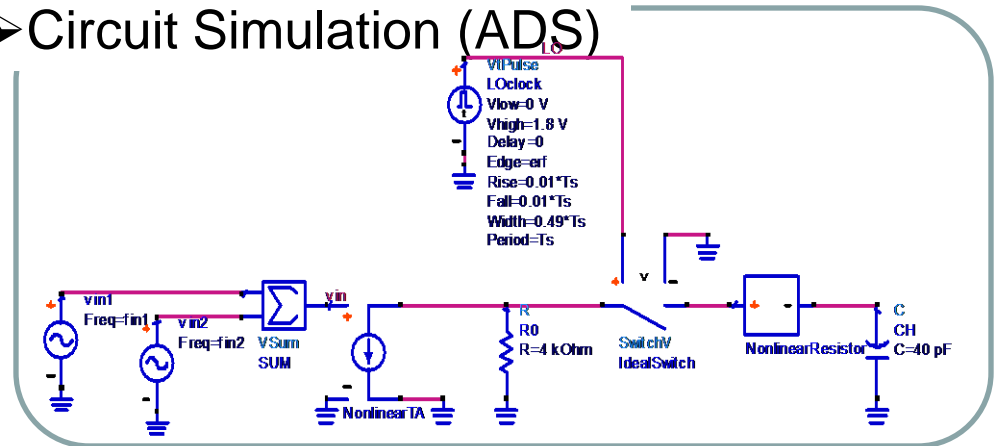
Simulation

◆ Simulation

➤ Simulation Parameter

P_{in}	-15 dBm	C_H	40 pF
f_{LO}	500 MHz	C_0	0.3 pF
R_0	4 k Ω	V_G	0 ~ 1.8 V
A	(Eq. 3)	$R(t)$	(Table.1)

➤ Circuit Simulation (ADS)

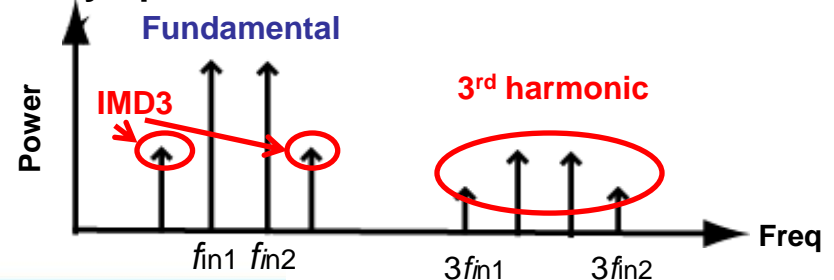


- Input Frequency : $f_{in1} + f_{LO}$ and $f_{in2} + f_{LO}$ (2 tone signal)
 \Rightarrow Output Frequency are f_{in1} , f_{in2} , and 3rd harmonic signal are down converted near $3f_{in1}$ and $3f_{in2}$ due to nonlinearity.

- Differential operation
 \Rightarrow 2nd distortion is canceled

- * $V_G \rightarrow$ gate voltage of switch
- * IMD3 \rightarrow 3rd Inter Modulation Distortion

Frequency Spectrum

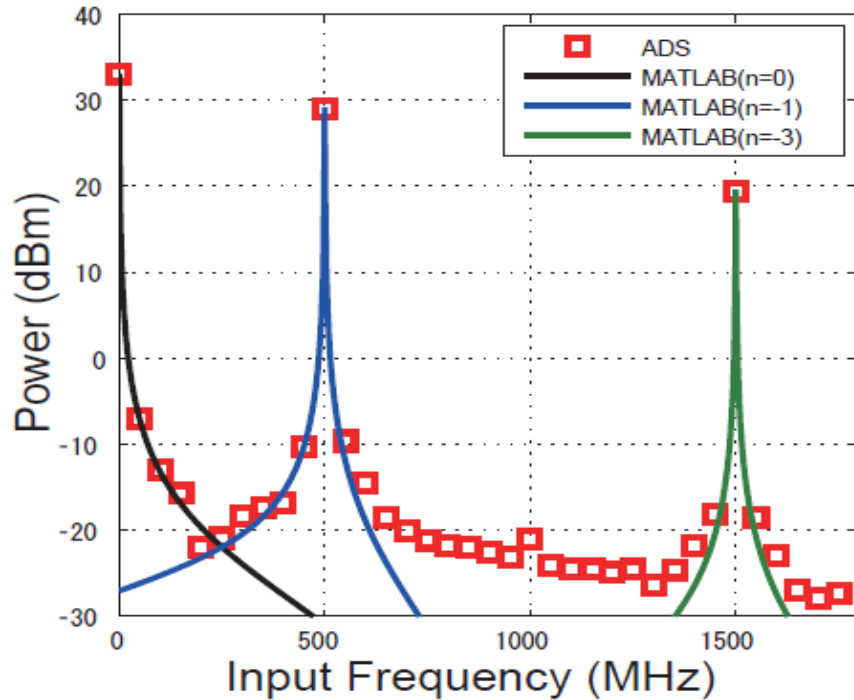


Simulation

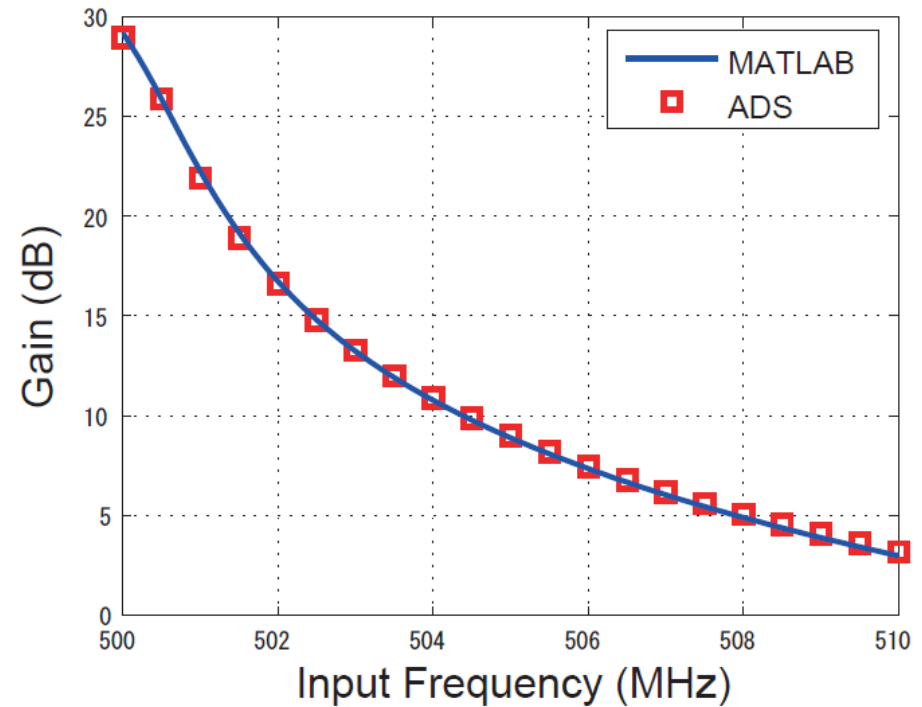
◆ LPTV System : Frequency Response

➤ First, we assume that charge sampling circuit is linear ($a_2=a_3=0$, $r_{on2}=r_{on3}=0$)

• Frequency Response



• Frequency Response near f_{Lo}

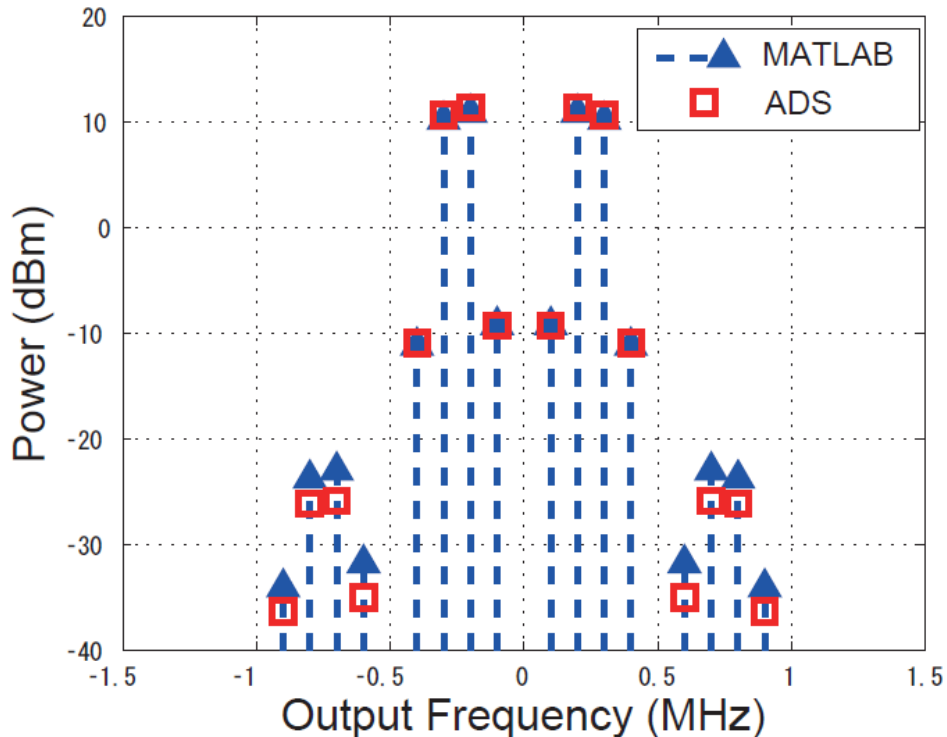


✓ If input frequency is near nf_{Lo} , MATLAB and ADS results are almost same.

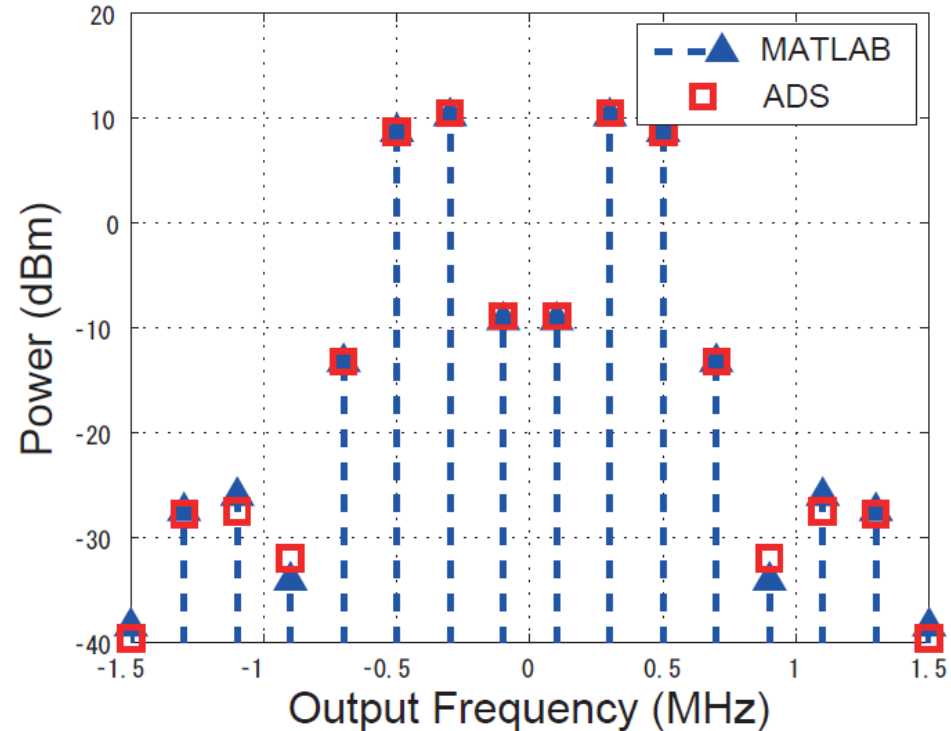
Simulation

◆ NLPTV System : Frequency Spectrum

- $f_{in1} = 0.2\text{MHz}$, $f_{in2} = 0.3\text{MHz}$



- $f_{in1} = 0.3\text{MHz}$, $f_{in2} = 0.5\text{MHz}$

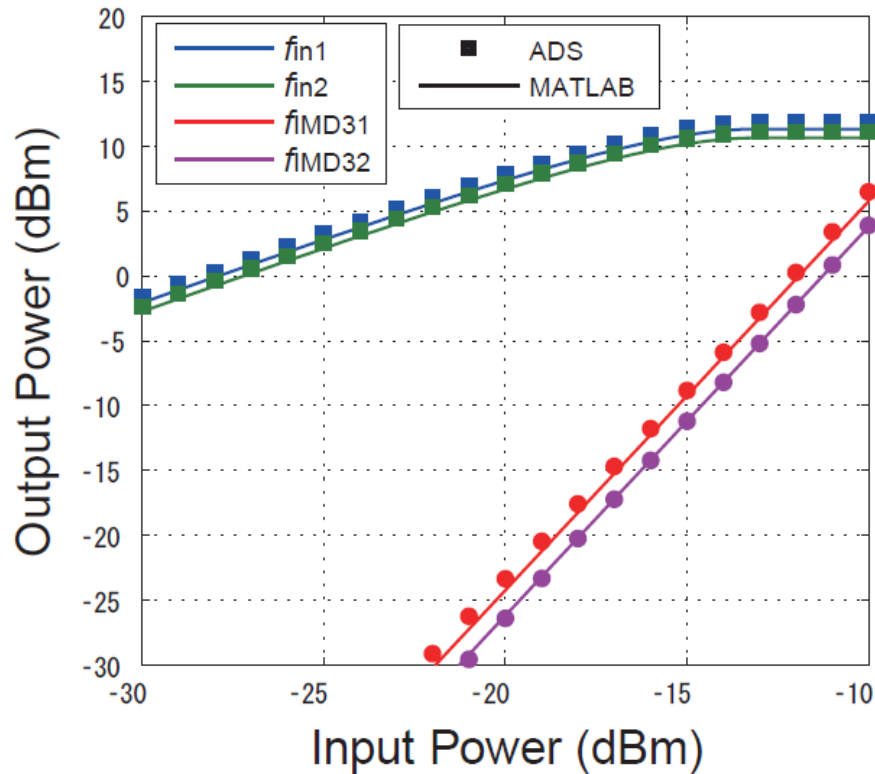


✓ From frequency spectrum, small difference is shown between MATLAB and ADS, but these are almost matched at fundamental and IMD3 components.

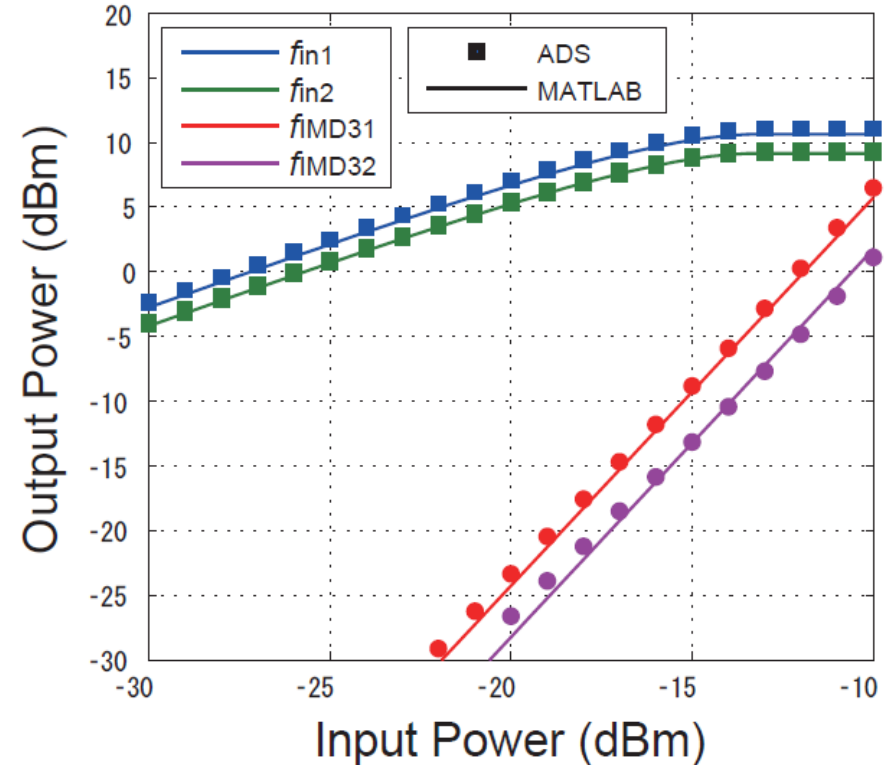
Simulation

◆ NLPTV System : AM-AM Characteristic

- $f_{in1} = 0.2\text{MHz}$, $f_{in2} = 0.3\text{MHz}$
($f_{IMD31} = 2f_{in1} - f_{in2} = 0.1\text{MHz}$, $f_{IMD32} = 2f_{in2} - f_{in1} = 0.4\text{MHz}$)



- $f_{in1} = 0.3\text{MHz}$, $f_{in2} = 0.5\text{MHz}$
($f_{IMD31} = 2f_{in1} - f_{in2} = 0.1\text{MHz}$, $f_{IMD32} = 2f_{in2} - f_{in1} = 0.7\text{MHz}$)



- ✓ Difference between MATLAB and ADS is less than 0.5dB.
- ✓ IIP3 (3rd Input Intercept Point) is about -4 ~ -3dBm.

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Conclusion and Future Work

◆ Conclusion

- The simple nonlinear periodic time-variant system can be analyzed with F-matrix, Volterra series function and Fourier series expansion.
- When input frequency is near the clock frequency, this analysis has same result with circuit simulation result.

◆ Future Work

- Improvement of this analysis model (more exact, more complex circuit architecture)
- Invention of efficient distortion compensation method.

Appendix.1

◆ Volterra Inverse



$$F_1(\omega_1) = 1$$

$$F_2(\omega_1, \omega_2) = 0$$

$$F_3(\omega_1, \omega_2, \omega_3) = 0$$

➤ If G is inverse function of H , G can be expressed as this.

$$H_1(\omega_1) = G_1^{-1}(\omega_1)$$

$$H_2(\omega_1, \omega_2) = \frac{-G_2(\omega_1, \omega_2)}{G_1(\omega_1 + \omega_2)G_1(\omega_1)G_1(\omega_2)}$$

$$H_3(\omega_1, \omega_2, \omega_3) = \left\{ -G_3(\omega_1, \omega_2, \omega_3) + \frac{2G_2(\omega_1, \omega_2 + \omega_3)G_2(\omega_2, \omega_3)}{G_1(\omega_2 + \omega_3)} \right\} / G_1(\omega_1 + \omega_2 + \omega_3)G_1(\omega_1)G_1(\omega_2)G_1(\omega_3)$$